Performance qualification of the detector on board the Spektr-UF (WSO-UV) Space Telescope

Ana I. Gómez de Castro, <u>María Frutos</u>, David Moya, Juan Carlos Vallejo, Ashley Thomson, Tom Conneely, James Milnes





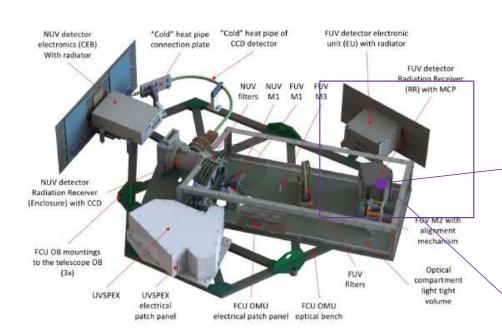






Field Camera Unit





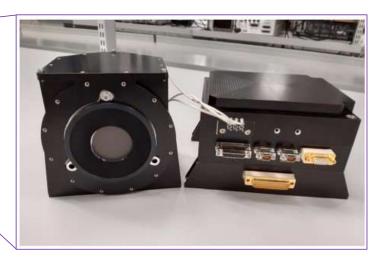
MCP

Field Camera Unit

Near Ultraviolet Channel (NUV): 174-315 nm.

Far Ultraviolet Channel (FUV): 115 and 180 nm.

Photon Detection Device



CMOS sensor





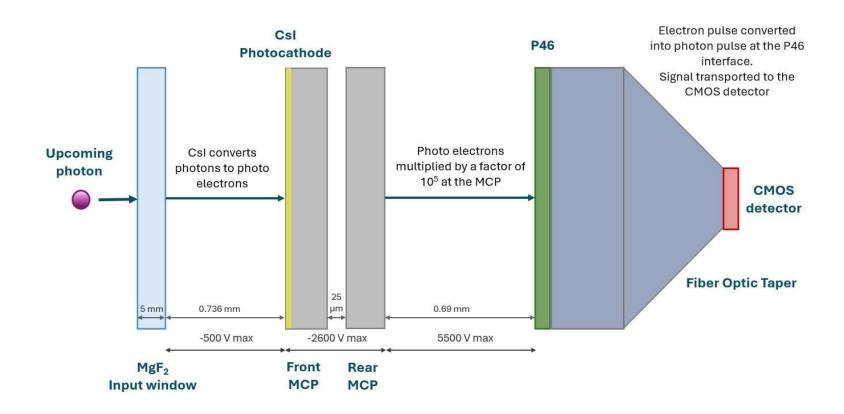
- -Detection, amplification and conversion of FUV radiation into digital data
- -Powering the RR
- -Commanding the detector
- -Acquiring and pre-processing images
- -Managing communications with the Camera Control Unit



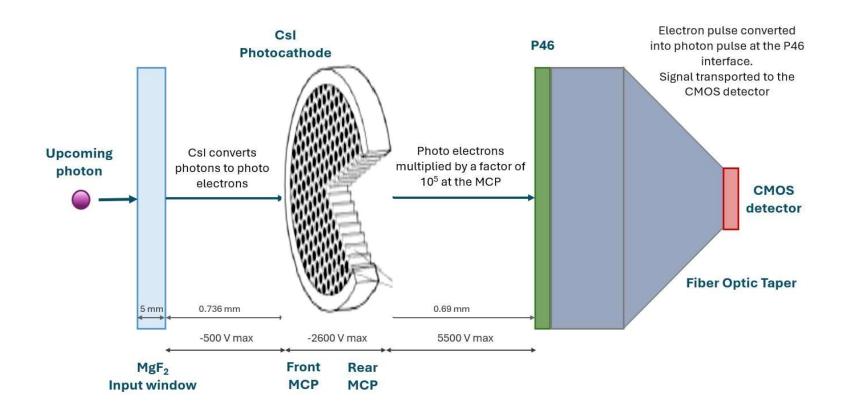




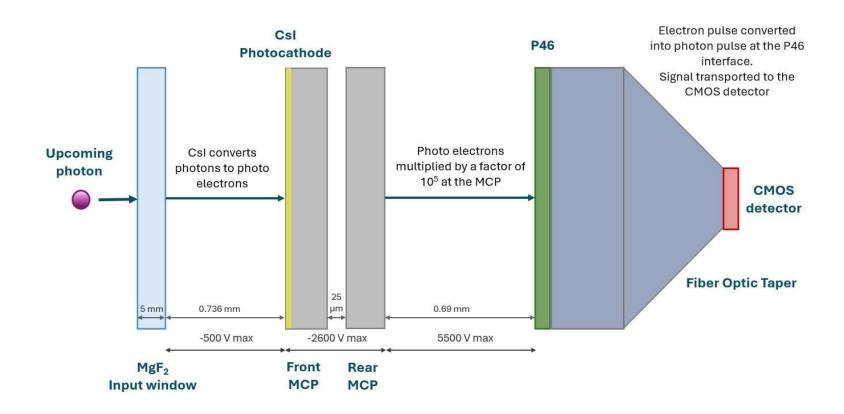








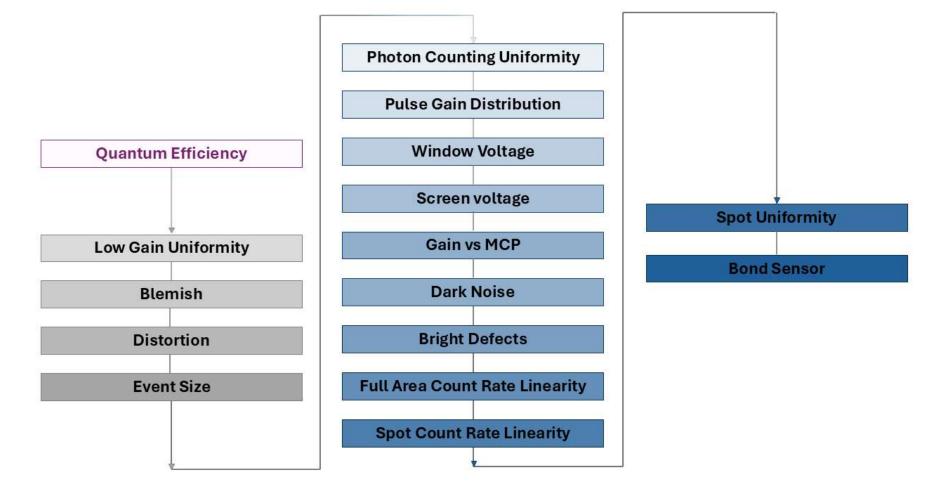








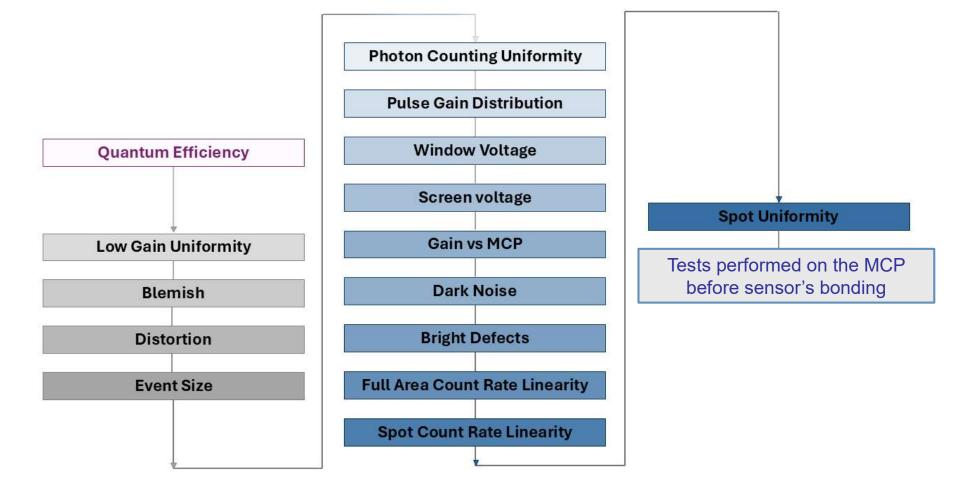




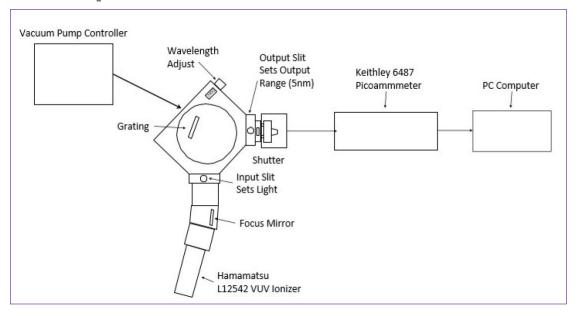












- 1.- The detector's photocurrent is measured at each of the wavelengths selected.
- 2.- Through comparison with an independently calibrated test cell, the detector's Quantum Efficiency is obtained.



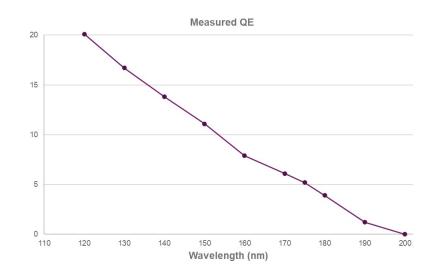






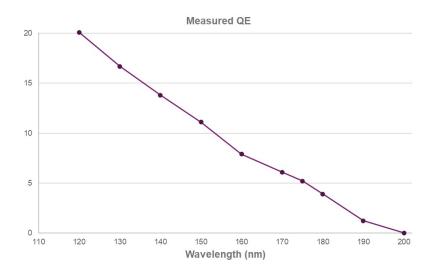
FM1

Wavelength (nm)	Measured QE
120	20.1
130	16.7
140	13.8
1 50	11.1
160	7.9
170	6.1
175	5.2
180	3.9
190	1.22
200	0



FM2

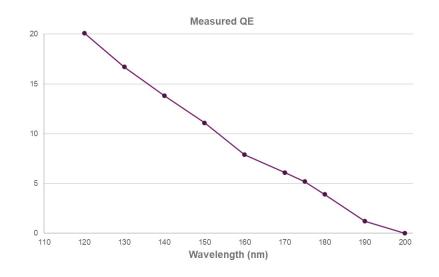
Wavelength (nm)	Measured QE
120	20.3
130	17.6
140	14.5
150	11.5
160	8.2
170	6.7
175	5.2
180	4.3
190	0.2
200	0





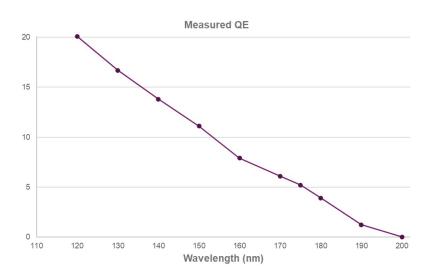
FM1

Wavelength (nm)	Measured QE
120	20.1
130	16.7
140	13.8
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200	0

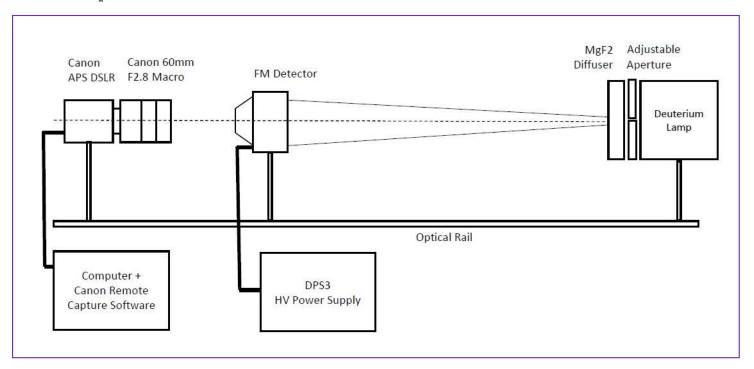


FM2

Wavelength (nm)	Measured QE
120	20.3
130	17.6
140	14.5
150	11.5
160	8.2
170	6.7
175	5.2
180	4.3
190	0.2
200	0







Low Gain Uniformity

Blemish

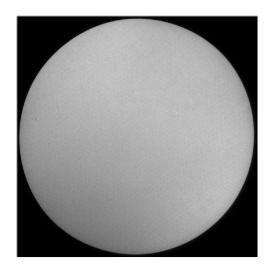
Distortion

Event Size

- 1.- The light source is placed at 1 m from the detector to ensure flat field illumination.
- 2.- Camera lens focused onto the output face of the MCP



Uniformity & Blemishes



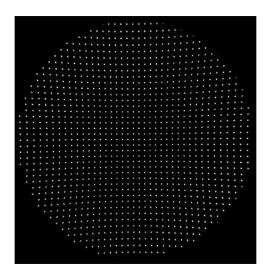
Standard deviation= 17

Mean= 17.5

SD/Mean= 10%

No recordable blemishes

Distortion



No significant distortion observed after placing a stainless steel mask on the detector's input window, with a regular grid of pinholess

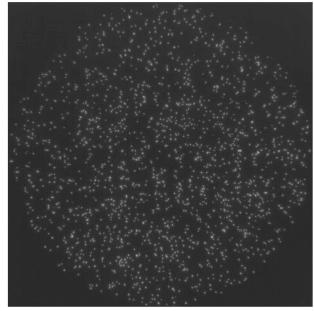
Single Photon Event Size

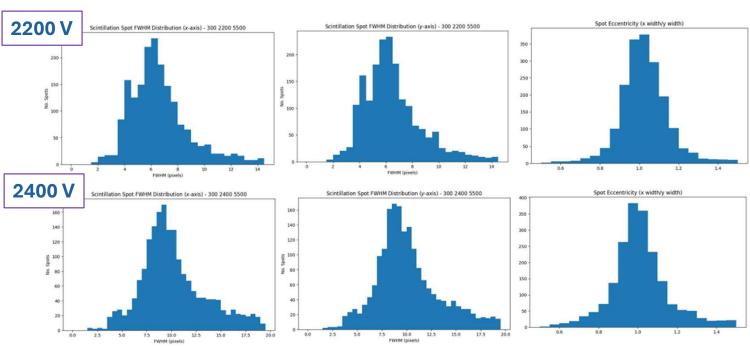


Signal spread over several pixels (to prevent saturation of the cell) but not over a too large number of pixels (to avoid a reduction of SNR)



Single Photon Event Size





Distribution of the detected photons by size

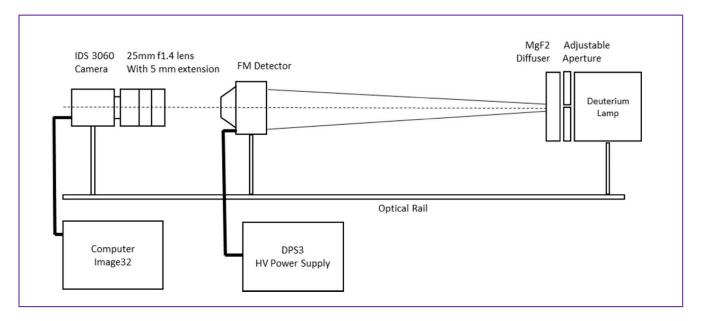
Top: MCP voltage 2200 V

- · Average event size 6.94 pixels
- · 1 Pixel 60 µm
- \cdot Event size 416.4 μm FWHM

Bottom: MCP voltage 2400 V

- · Average event size 10.9 pixels
- · 1 Pixel 60 µm
- \cdot Event size 654.0 μm FWHM





Photon Counting Uniformity

Pulse Gain Distribution

Window Voltage

Screen voltage

Gain vs MCP

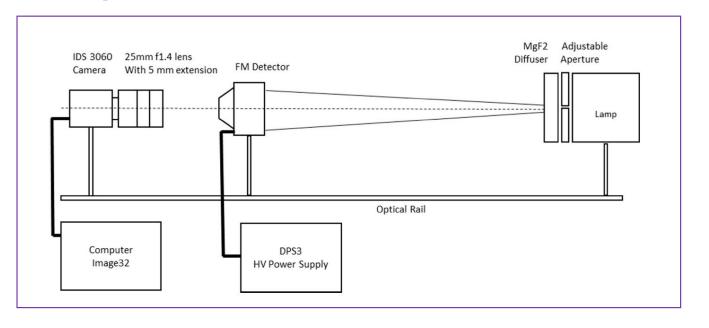
Dark Noise

Bright Defects

Full Area Count Rate Linearity

Spot Count Rate Linearity





Photon Counting Uniformity

Pulse Gain Distribution

Window Voltage

Screen voltage

Gain vs MCP

Dark Noise

Bright Defects

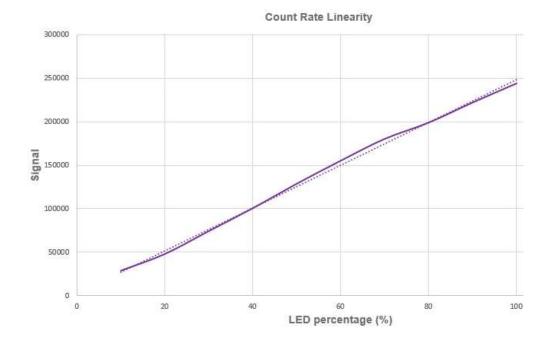
Full Area Count Rate Linearity

Spot Count Rate Linearity



- 1.- Voltage at the MCP adjusted to a photon rate over 200.000 cps.
- 2.- Light level of the Adjustable Led Source decreased in intervals of 10%

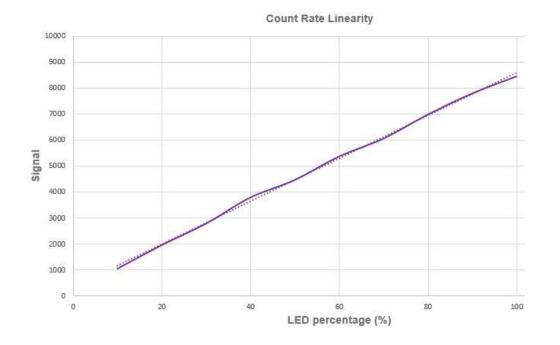
LED Percentage	Signal	Deviation
10	28501	-3.7
20	47701	8.4
30	74151	3.2
40	100482	0.7
50	128691	-2.3
60	155210	-3.2
70	180352	-3.1
80	199076	0.2
90	222254	0.8
100	244299	1.8



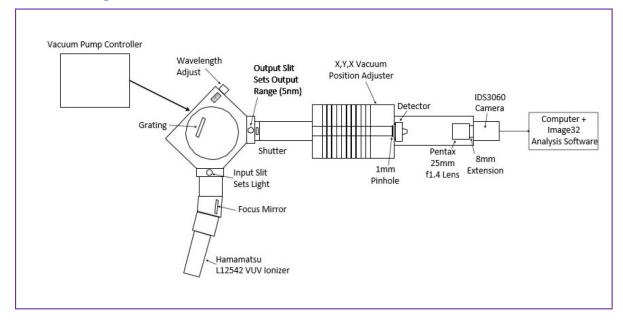


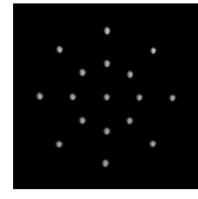
- 1.- 210 µm diameter pinhole placed before the detector.
- 2.- Voltage at the MCP adjusted to a photon rate over 8.000 cps.
- 3.- Light level of the Adjustable Led Source decreased in intervals of 10%

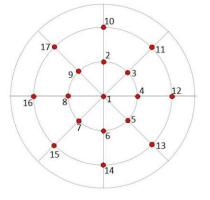
LED Percentage	Signal	Deviation
10	1050	6.71
20	1959	-0.09
30	2789	-0.01
40	3795	-4.82
50	4470	-0.4
60	5379	-1.8
70	6065	0.82
80	6993	-0.66
90	7805	-0.34
100	8464	1.7











Position	Result	Deviation
1	46202	-1.4
2	46250	-1.3
3	46702	-0.3
4	46890	0.1
5	46073	-1.7
6	46779	-0.2
7	46441	-0.9
8	45905	-2
9	45486	-2.9
10	48309	3.1
11	48227	2.9
12	46875	0
13	46590	-0.6
14	48505	3.5
15	48111	2.7
16	47061	0.4
17	46653	-0.4
Mean	46886	-

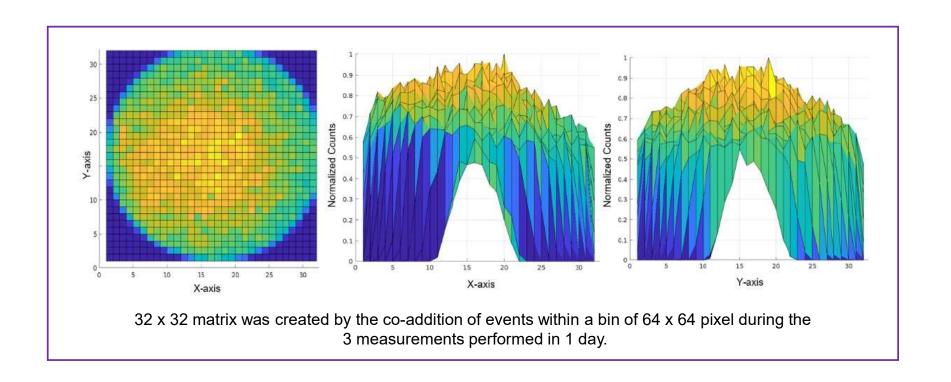
- 1.- The light beam passes through a 1 mm diameter pinhole.
- 2.- Photon-counting integration.
- 3.- Pinhole moved to another position of the detector's surface.
- 4.- Measurement repeated.
- 5.- Calculation of mean and standard deviation.



- 9 measurements: 3 measurements/day taken during 3 consecutive days.
- Frame rate: 60 FPS.
- 198 frames/measurement.
- Events extracted frame by frame and classified in a list showing the x and y coordinates of the centroids.
- Matrices have been created by the co-addition of events within a bin of the adequate size to reach suitable photon statistics.

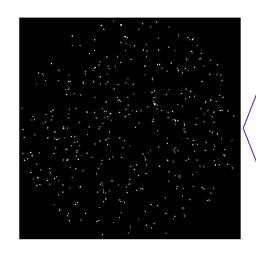


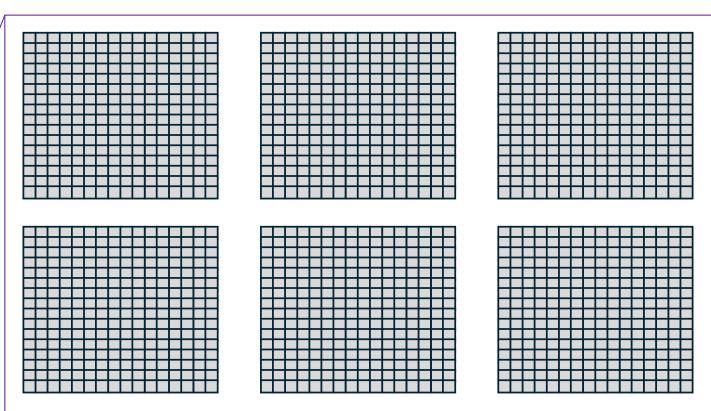
Spatial Uniformity. FM1





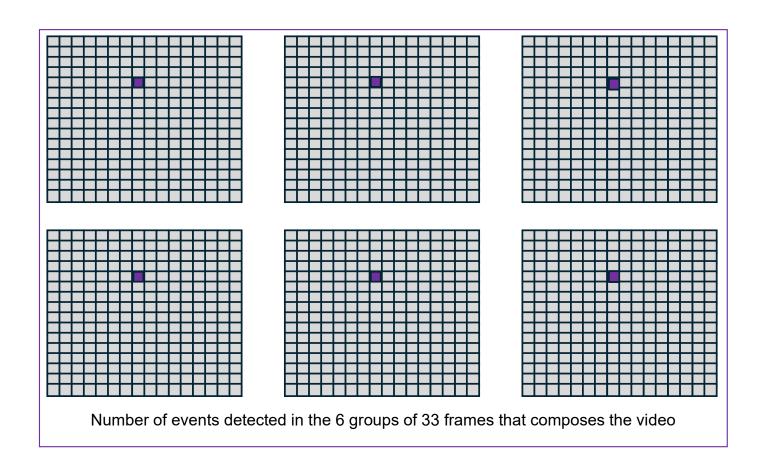
Temporary Stability. FM1





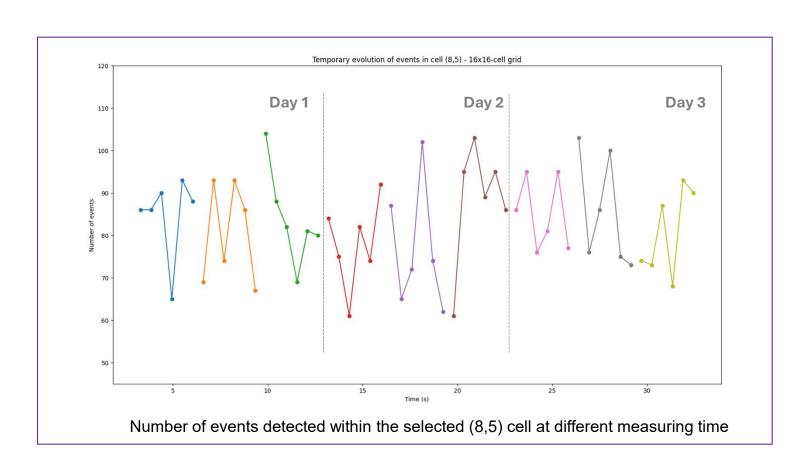
16 x 16 matrices were created for each measurement after the co-addition of the extracted events every 33 frames within a bin of 128 x 128 pixel





3 measurements/day 3 days of measurements





No significative variations were observed in the number of events detected every 33 frames, in all the cells generated during the three days of measurements



- Both photon counting detector units have been completly qualified.
- Their performance meets the technical requirements of the WSO-UV scientific project.
- Environmental and Mechanical Tests have been succesfully performed.
- The CMOS sensors have been bonded.
- Pending electronical integration and validation.

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